Public Data-based Report

Validation Report Service

Cryo-EM Map Validation Report

Report to assess Cryo-EM Volume Map at Level(s) 0

This report has been generated based on data publicly available at EMDB.

Basic Entry Information:

EMDB ID: EMD-1818
Title: Structure of S. cerevisiae anaphase promoting complex-Cdh1-KENbox peptide
Authors: See EMDB entry link
Deposited on: 2010-10-27T00:00:00
Reported Resolution: (not reported)

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Last update: **August 23, 2024, 10:12am**

Context

Cryo-electron microscopy is currently one of the most active techniques in Structural Biology. The number of maps deposited at the Electron Microscopy Data Bank is rapidly growing every year and keeping the quality of the submitted maps is essential to maintain the scientific quality of the field. The ultimate quality measure is the consistency of the map and an atomic model. However, this is only possible for high resolution maps. Over the years there have been many suggestions about validation measures of 3DEM maps. Unfortunately, most of these measures are not currently in use for their spread in multiple software tools and the associated difficulty to access them. To alleviate this problem, we made available a validation grading system that evaluate the information provided to assess the map.
This system grades a map from 0 to 5 depending on the amount of information available. In this way, a map could be validated at Level 0 (the deposited map), 1 (two half maps), 2 (2D classes), 3 (particles), 4 (... + angular assignment), 5 (... + micrographs and coordinates). In addition, we can have three optional qualifiers: A (... + atomic model), W (... + image processing workflow), and O (... + other techniques).

This Validation Report Service is explained in more detail in this paper. For more information about the different methods and softwares used for this report, see the references here.

Summarized overall quality

The map seems to be well centered. There is no problem with the suggested threshold. There seems to be a problem with the map's background (see Sec. 2.3).

The overall score (passing tests) of this report is 2 out of 3 evaluable items.

Some programs may not work properly since resolution parameter has not been reported.

0.a Mass analysis	Sec. 2.1	OK
0.b Mask analysis	Sec. 2.2	OK
0.c Background analysis	Sec. 2.3	2 warnings
0.d B-factor analysis	Sec. 2.4	Does not apply
0.e DeepRes	Sec. 2.5	Does not apply
0.e Local B-factor	Sec. 2.6	Does not apply
0.g Local Occupancy	Sec. 2.7	Does not apply
0.h Deep hand	Sec. 2.8	Does not apply

Summary of the warnings across sections.

Section 2.3 (0.c Background analysis)

1. **The null hypothesis that the background mean is 0 has been rejected because the p-value of the comparison is smaller than 0.001**
2. **There is a significant proportion of outlier values in the background (cdf5 ratio=11823.40)**

Contents

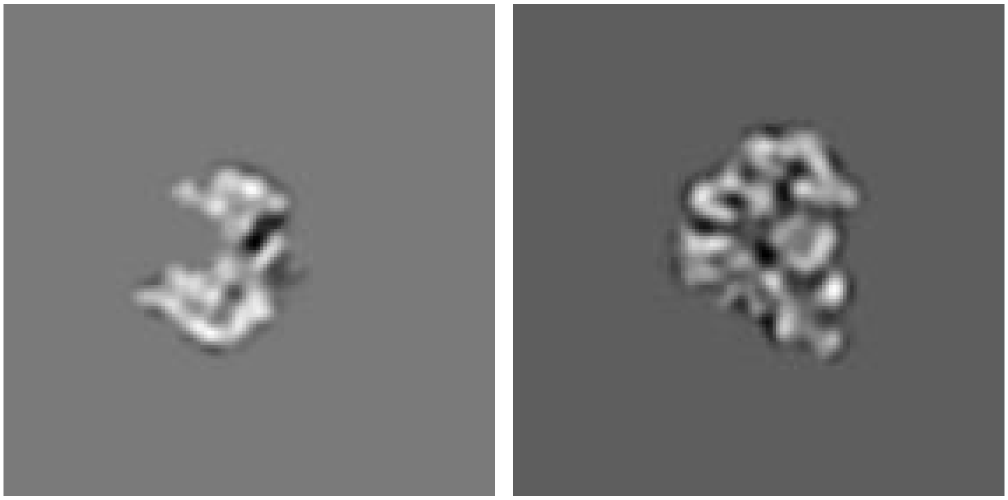
1 Input data

Input map: emd_1818.map
SHA256 hash: cd30d4485694c974c498f27bd0c1f65311c8315cde7f0d924809aaba3b8f67fc
Voxel size: 3.470000 (Å)
Visualization threshold: 0.153000
Resolution estimated by user: (not reported)

Orthogonal slices of the input map

Explanation:
In the orthogonal slices of the map, the noise outside the protein should not have any structure (stripes going out, small blobs, particularly high or low densities, ...)

Results:
See Fig. 1.



(a) X Slice 70

(b) Y Slice 70

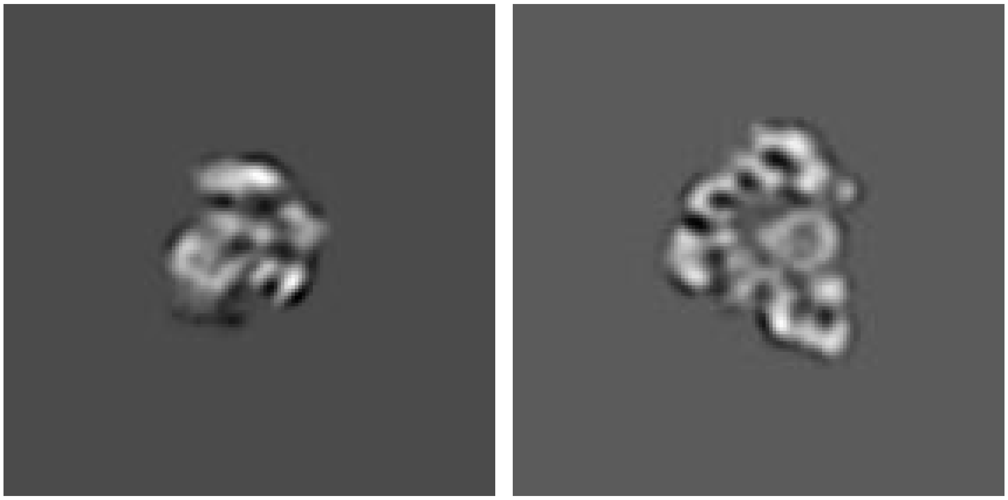
(c) Z Slice 70

Figure 1: Central slices of the input map in the three dimensions

Orthogonal slices of maximum variance of the input map

Results:

See Fig. 2.



(a) X Slice 82

(b) Y Slice 66

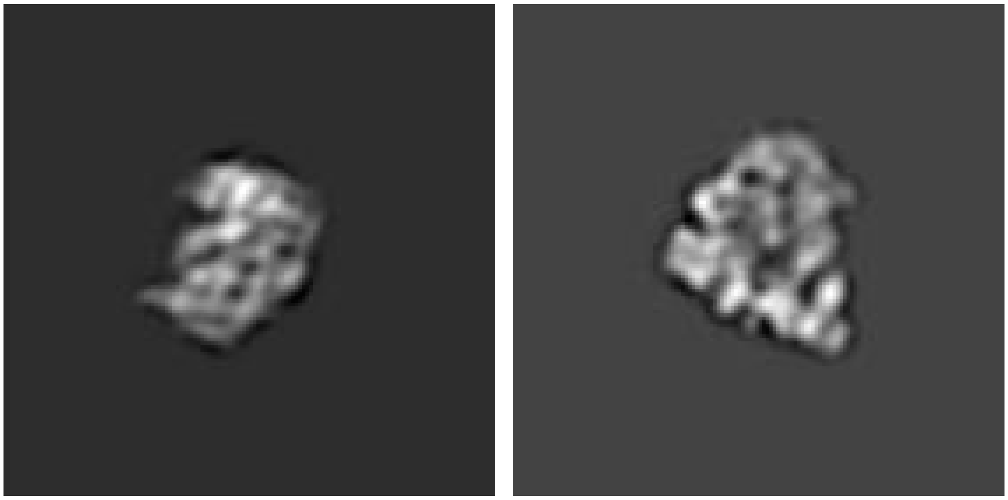
(c) Z Slice 83

Figure 2: Slices of maximum variation in the three dimensions

Orthogonal projections of the input map

Explanation:
In the projections there should not be stripes (this is an indication of directional overweighting, or angular attraction), and there should not be a dark halo around or inside the structure (this is an indication of incorrect CTF correction or the reconstruction of a biased map).

Results:
See Fig. 3.



(a) X Projection (b) Y Projection

(c) Z Projection

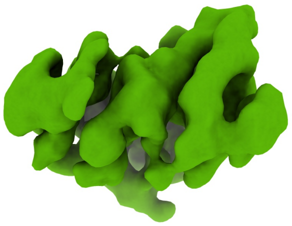
Figure 3: Projections in the three dimensions

Isosurface views of the input map

Explanation:
An isosurface is the surface of all points that have the same gray value. In these views there should not be many artifacts or noise blobs around the map.

Results:
See Fig. 4.

(a) View 1 (b) View 2



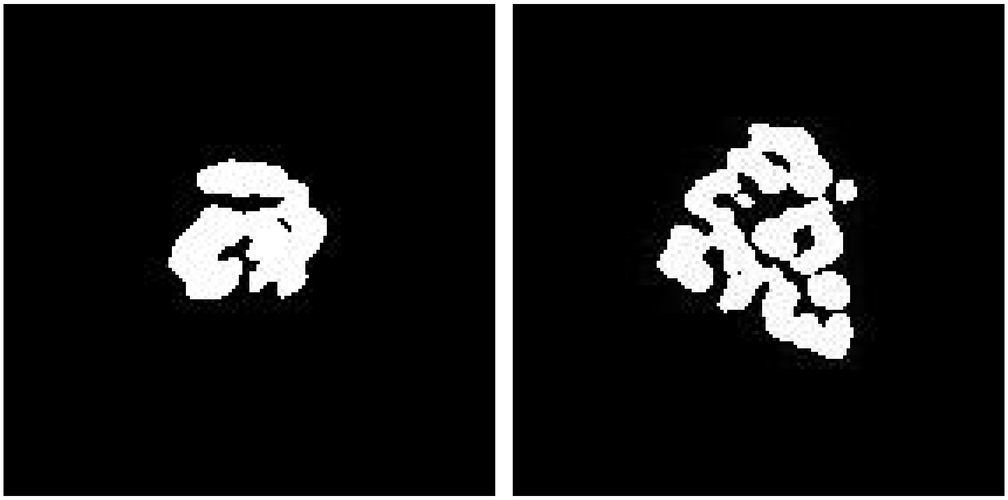
(c) View 3

Figure 4: Isosurface at threshold=0.153000. Views generated by ChimeraX at a the following X, Y, Z angles: View 1 (0, -90, -90), View 2 (-90, 0, -90), View 3 (0, 0, 0).

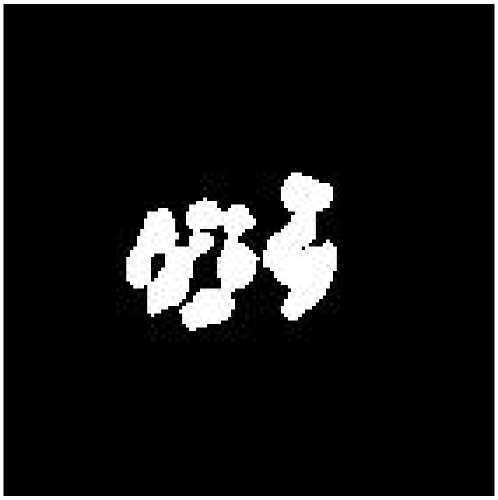
Orthogonal slices of maximum variance of the mask with hard borders

Explanation:
The mask with hard borders has been calculated at the suggested threshold 0.153000, the largest connected component was selected, and then dilated by 2Å.

Results:
See Fig. 5.



(a) X Slice 84 (b) Y Slice 65



(c) Z Slice 74

Figure 5: Slices of maximum variation in the three dimensions of the mask with hard borders

Orthogonal slices of maximum variance of the mask with soft borders

Explanation:

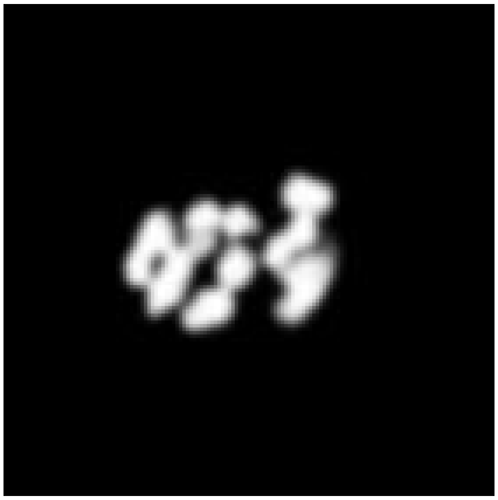
The mask with soft borders has been calculated at the suggested threshold 0.153000, the largest connected component was selected, and then dilated by

2Å.

Results:
See Fig. 6.

(a) X Slice 84

(b) Y Slice 65



(c) Z Slice 73

Figure 6: Slices of maximum variation in the three dimensions of the mask with soft borders

2 Level 0 analysis

2.1 Level 0.a Mass analysis

Explanation:
The reconstructed map must be relatively well centered in the box, and there should be at least 30Å (the exact size depends on the CTF) on each side to make sure that the CTF can be appropriately corrected.

Results:
The space from the left and right in X are 117.98 and 138.80 Å, respectively. There is a decentering ratio (abs(Right-Left)/Size)% of 4.29%

The space from the left and right in Y are 128.39 and 170.03 Å, respectively. There is a decentering ratio (abs(Right-Left)/Size)% of 8.57%

The space from the left and right in Z are 142.27 and 145.74 Å, respectively. There is a decentering ratio (abs(Right-Left)/Size)% of 0.71%

The center of mass is at (x,y,z)=(67.87, 65.92, 71.53). The decentering of the center of mass (abs(Center)/Size)% is 1.52, 2.91, and 1.09, respectively.

Automatic criteria: The validation is OK if 1) the decentering and center of mass less than 20% of the map dimensions in all directions, and 2) the extra space on each direction is more than 20% of the map dimensions. For local and focused refinement, or similar, warnings are expected.

STATUS: OK

2.2 Level 0.b Mask analysis

Explanation:
The map at the suggested threshold should have most of its mass concentrated in a single connected component. It is normal that after thresholding there are a few thousands of very small, disconnected noise blobs. However, there total mass should not exceed 10%. The raw mask (just thresholding) and the mask constructed for the analysis (thresholding + largest connected component + dilation) should significantly overlap. Overlap is defined by the overlapping coefficient (size(Raw AND Constructed)/size(Raw)) that is a number between 0 and 1, the closer to 1, the more they agree.

Results:

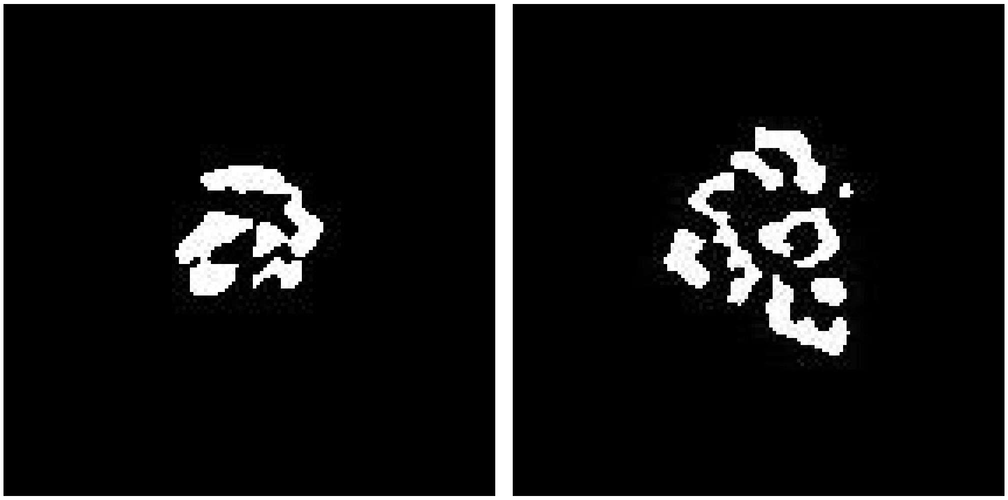
Raw mask: At threshold 0.153000, there are 1 connected components with a total number of voxels of 27344 and a volume of 1142484.90 Å^3 (see Fig. 7). The size and percentage of the total number of voxels for the raw mask are listed below (up to 95% of the mass or the first 100 clusters, whatever happens first), the list contains (No. voxels (volume in Å^3), percentage, cumulated percentage):

(27344 (1142484.90), 100.00, 100.00)

Number of components to reach 95% of the mass: 1

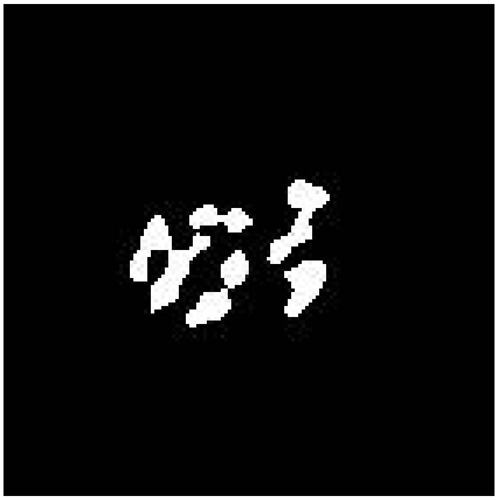
The average size of the remaining 0 components is nan voxels (nan Å^3). Their size go from 27344 voxels (1142484.90 Å^3) to 27344 voxels (1142484.90 Å^3).

The slices of the raw mask can be seen in Fig. 7.



(a) X Slice 84

(b) Y Slice 65



(c) Z Slice 73

Figure 7: Maximum variance slices in the three dimensions of the raw mask

The following table shows the variation of the mass enclosed at different thresholds (see Fig. 8):

Threshold	**Voxel mass**	**Molecular mass(kDa)**	**# Aminoacids**
0.0284	48543.00	1680.38	15276.19
0.0567	43065.00	1490.75	13552.30
0.0851	38205.00	1322.52	12022.88
0.1134	33482.00	1159.02	10536.58
0.1418	29078.00	1006.57	9150.67
0.1702	24981.00	864.75	7861.37
0.1985	21067.00	729.26	6629.66
0.2269	17349.00	600.56	5459.63
0.2553	14080.00	487.40	4430.89
0.2836	11178.00	386.94	3517.65
0.3120	8652.00	299.50	2722.73
0.3403	6493.00	224.76	2043.31
0.3687	4745.00	164.25	1493.22
0.3971	3383.00	117.11	1064.61
0.4254	2375.00	82.21	747.40
0.4538	1537.00	53.21	483.68
0.4822	948.00	32.82	298.33
0.5105	566.00	19.59	178.12
0.5389	337.00	11.67	106.05
0.5672	205.00	7.10	64.51
0.5956	106.00	3.67	33.36
0.6240	54.00	1.87	16.99
0.6523	18.00	0.62	5.66
0.6807	6.00	0.21	1.89

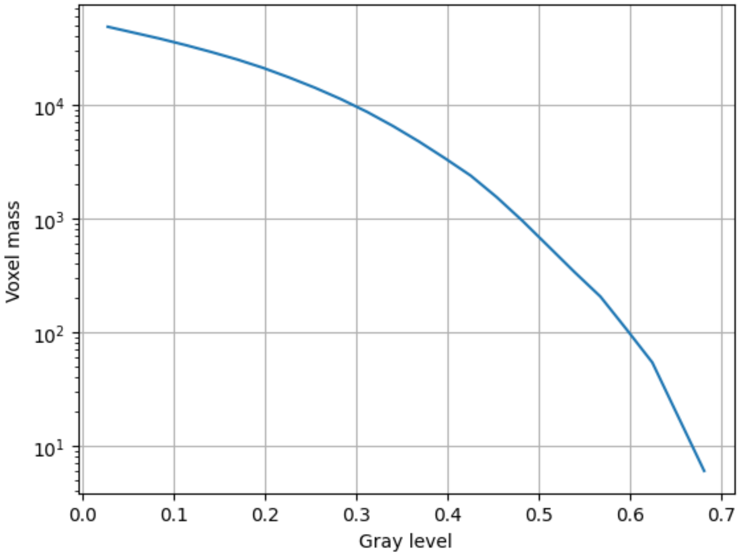


Figure 8: Voxel mass as a function of the gray level.

Constructed mask: After keeping the largest component of the previous mask and dilating it by 2Å, there is a total number of voxels of 49408 and a volume of 2064361.25 $Å^3$. The overlap between the raw and constructed mask is 1.00.

Automatic criteria: The validation is OK if 1) to keep 95% of the mass we need to keep at most 5 connected components; and 2) the average volume of the blobs outside the given threshold has a size smaller than $5Å^3$; and 3) the overlap between the raw mask and the mask constructed for the analysis is larger than 75%.

STATUS: OK

2.3 Level 0.c Background analysis

Explanation:
Background is defined as the region outside the macromolecule mask. The background mean should be zero, and the number of voxels with a very low or very high value (below 5 standard deviations of the noise) should be very

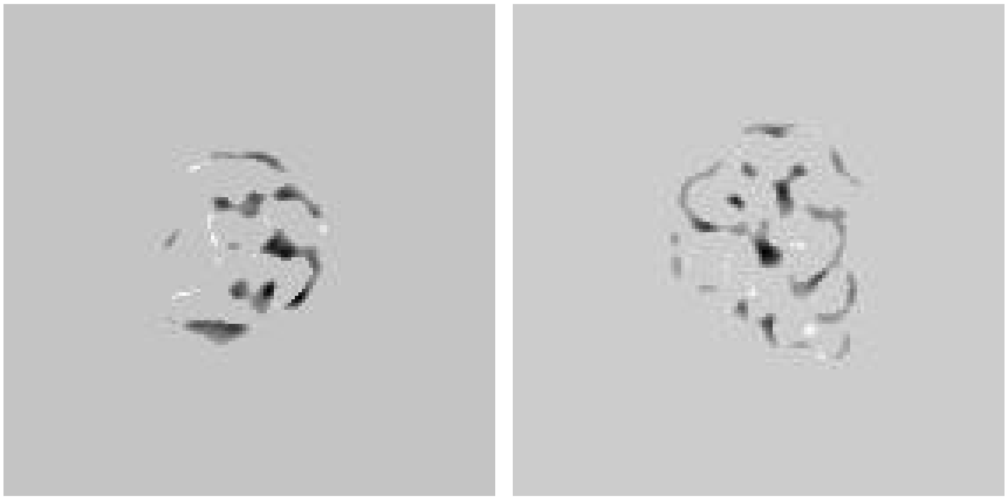
small and they should be randomly distributed without any specific structure. Sometimes, you can see some structure due to the symmetry of the structure.

Results:

The null hypothesis that the background mean is 0 was tested with a one-sample Student's t-test. The resulting t-statistic and p-value were -127.23 and 0.000000, respectively.

The mean and standard deviation (sigma) of the background were -0.000773 and 0.009969. The percentage of background voxels whose absolute value is larger than 5 times the standard deviation is 0.68 % (see Fig. 9). The same percentage from a Gaussian would be 0.000057% (ratio between the two percentages: 11823.398766).

Slices of the background beyond 5*sigma can be seen in Fig. 9.



(a) X Slice 80

(b) Y Slice 71

(c) Z Slice 71

Figure 9: Maximum variance slices in the three dimensions of the parts of the background beyond 5*sigma

Automatic criteria: The validation is OK if 1) the p-value of the null hypothesis that the background has 0 mean is larger than 0.001; and 2) the number of voxels above or below 5 sigma is smaller than 20 times the amount expected for a Gaussian with the same standard deviation whose mean is 0.

WARNINGS: 2 warnings

1. **The null hypothesis that the background mean is 0 has been rejected because the p-value of the comparison is smaller than 0.001**
2. **There is a significant proportion of outlier values in the background (cdf5 ratio=11823.40)**

2.4 Level 0.d B-factor analysis

Explanation:
The B-factor line (see this link for more details) fitted between 15Åand the resolution reported should have a slope that is between 0 and 300 Å^2.
Results:

This method cannot be applied to maps with no resolution reported.

STATUS: Does not apply

2.5 Level 0.e Local resolution with DeepRes

Explanation:
DeepRes (see this link for more details) measures the local resolution using a neural network that has been trained on the appearance of atomic structures at different resolutions. Then, by comparing the local appearance of the input map to the appearance of the atomic structures a local resolution label can be assigned.

Results:

This method cannot be applied to maps with no resolution reported.

STATUS: Does not apply

2.6 Level 0.f Local B-factor

Explanation:
LocBfactor (see this link for more details) estimates a local resolution B-factor by decomposing the input map into a local magnitude and phase term using the spiral transform.

Results:

This method cannot be applied to maps with no resolution reported.

STATUS: Does not apply

2.7 Level 0.g Local Occupancy

Explanation:
LocOccupancy (see this link for more details) estimates the occupancy of a voxel by the macromolecule.

Results:

This method cannot be applied to maps with no resolution reported.

STATUS: Does not apply

2.8 Level 0.h Hand correction

Explanation:
Deep Hand (see this link for more details) determines the correction of the hand for those maps with a resolution smaller than 5Å. The method calculates a value between 0 (correct hand) and 1 (incorrect hand) using a neural network to assign its hand.

Results:

This method cannot be applied to maps with no resolution reported.

STATUS: Does not apply