



Public Data-based Report



Validation Report Service

Cryo-EM Map Validation Report

Report to assess Cryo-EM Volume Map at Level(s) 0, A

This report has been generated based on data publicly available at [EMDB](#).

Basic Entry Information:

EMDB ID: [EMD-24201](#)

PDB ID: [7n69](#)

Title: Late pre-fusion state of EEEV (pH 5.5) with localized reconstruction

Authors: [See EMDB entry link](#)

Deposited on: 2021-06-07T00:00:00

Reported Resolution: 14.1 Å

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Last update: **September 13, 2026, 8:51am**

Context

Cryo-electron microscopy is currently one of the most active techniques in Structural Biology. The number of maps deposited at the [Electron Microscopy Data Bank](#) is rapidly growing every year and keeping the quality of the submitted maps is essential to maintain the scientific quality of the field. The ultimate quality measure is the consistency of the map and an atomic model. However, this is only possible for high resolution maps. Over the years there have been many suggestions about validation measures of 3DEM maps. Unfortunately, most of these measures are not currently in use for their spread in multiple software tools and the associated difficulty to access them. To alleviate this problem, we made available a validation grading system that evaluate the information provided to assess the map.

This system grades a map from 0 to 5 depending on the amount of information available. In this way, a map could be validated at Level 0 (the deposited map), 1 (two half maps), 2 (2D classes), 3 (particles), 4 (... + angular assignment), 5 (... + micrographs and coordinates). In addition, we can have three optional qualifiers: A (... + atomic model), W (... + image processing workflow), and O (... + other techniques). To know more about this service read this [paper](#)

This Validation Report Service uses Scipion (see this [link](#) for more detail) as workflow engine and ChimeraX (see this [link](#) for more detail) to generate the 3D views. For more information about the different methods and softwares used for this report, see the references [here](#).



Summarized overall quality

The map seems to have some problem in its centering or extra space (see Sec. 2.1). There seems to be a problem with the suggested threshold (see Sec. 2.2). There seems to be a problem with the map's background (see Sec. 2.3). According to phenix, it seems that there might be some mismatch between the map and its model (see Sec. 4.1).

The average resolution of the map estimated is 16.7Å . The resolution reported by the user was 14.1Å.

The overall score (passing tests) of this report is 0 out of 4 evaluable items.

0.a Mass analysis	Sec. 2.1	7 warnings
0.b Mask analysis	Sec. 2.2	2 warnings
0.c Background analysis	Sec. 2.3	2 warnings
0.d B-factor analysis	Sec. 2.4	Does not apply
A.a Phenix validation	Sec. 4.1	1 warnings
A.d Map-Model Guinier analysis	Sec. 4.2	Does not apply
A.e MapQ	Sec. 4.3	Does not apply
A.f EMRinger	Sec. 4.4	Does not apply
A.g DAQ	Sec. 4.5	Does not apply

Summary of the warnings across sections.

Section 2.1 (0.a Mass analysis)

1. The volume might be significantly decentered in X.
2. The volume might be significantly decentered in Z.
3. There could be little space from X left to effectively correct for the CTF.
4. There could be little space from Z left to effectively correct for the CTF.
5. The center of mass in X may be significantly shifted. This is common when the refinement is applied exclusively to one protein region.
6. The center of mass in Y may be significantly shifted. This is common when the refinement is applied exclusively to one protein region.
7. The center of mass in Z may be significantly shifted. This is common when the refinement is applied exclusively to one protein region.

Section 2.2 (0.b Mask analysis)

1. There might be a problem with noise and artifacts, because the average noise blob has a volume of 42.728168 Å³.
2. There might be a problem in the construction of the mask, because the overlap is smaller than 0.75. A common reason is that the suggested threshold causes too many disconnected components.

Section 2.3 (0.c Background analysis)

1. The null hypothesis that the background mean is 0 has been rejected because the p-value of the comparison is smaller than 0.001
2. There is a significant proportion of outlier values in the background (cdf5 ratio=1375.86)

Section 4.1 (A.a Phenix validation)

1. The model-map FSC resolution value (FSC=0.5) is missing. Skipping consistency check with the user-reported resolution.

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1 Input data

Input map: emd_24201.map

SHA256 hash: be6ae98d092c0da725ea9c724b5021ea511b143f695ab9d12b14cf77334cb0b6

Voxel size: 3.496000 (Å)

Visualization threshold: 1.500000

Resolution estimated by user: 14.1

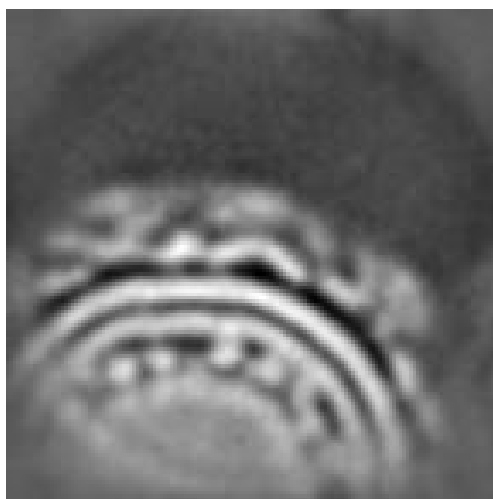
Orthogonal slices of the input map

Explanation:

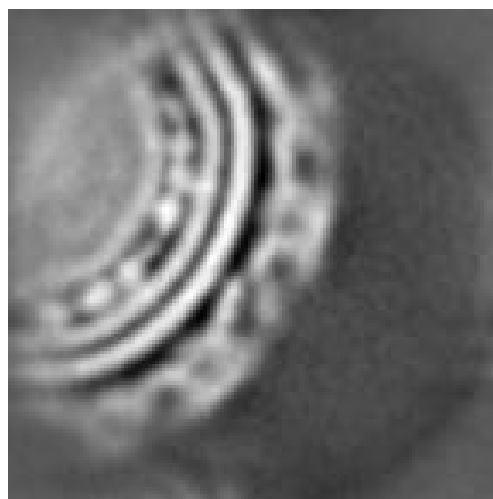
In the orthogonal slices of the map, the noise outside the protein should not have any structure (stripes going out, small blobs, particularly high or low densities, ...)

Results:

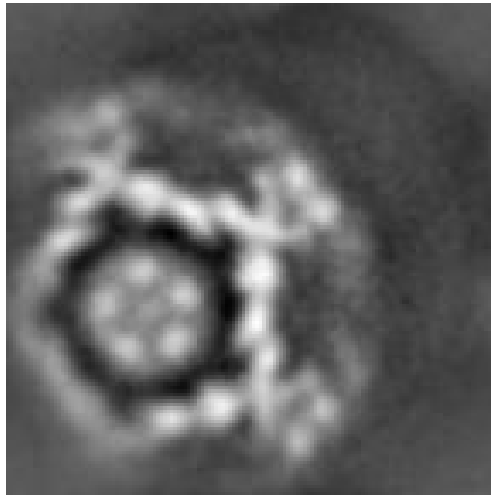
See Fig. 1.



(a) X Slice 72



(b) Y Slice 72



(c) Z Slice 72

Figure 1: Central slices of the input map in the three dimensions

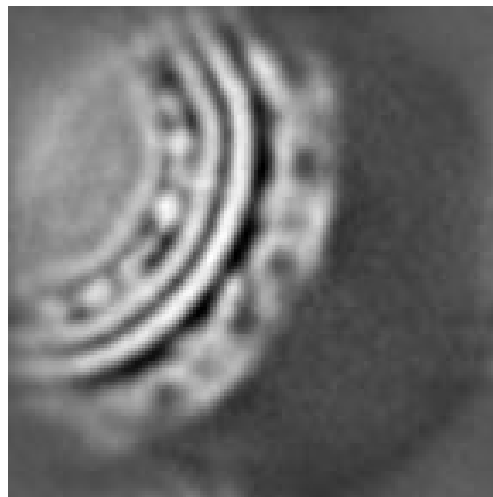
Orthogonal slices of maximum variance of the input map

Results:

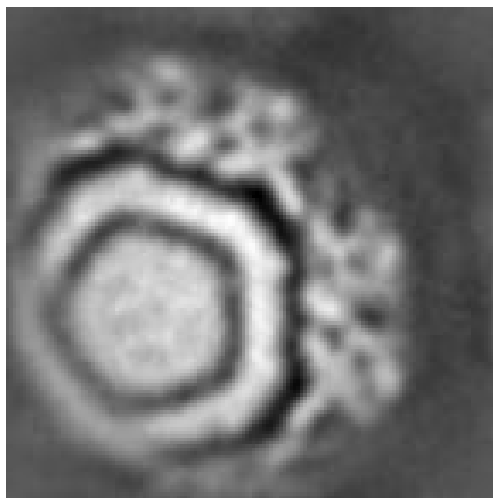
See Fig. 2.



(a) X Slice 68



(b) Y Slice 73



(c) Z Slice 60

Figure 2: Slices of maximum variation in the three dimensions

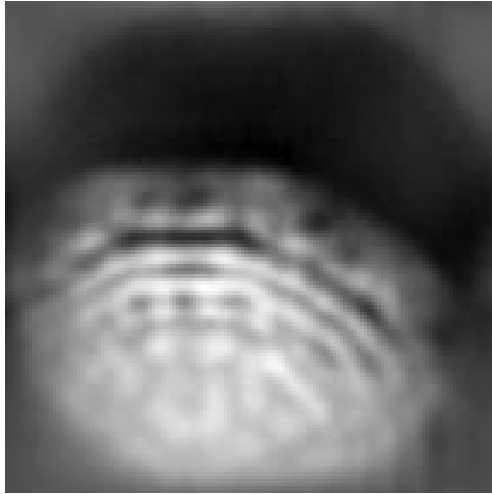
Orthogonal projections of the input map

Explanation:

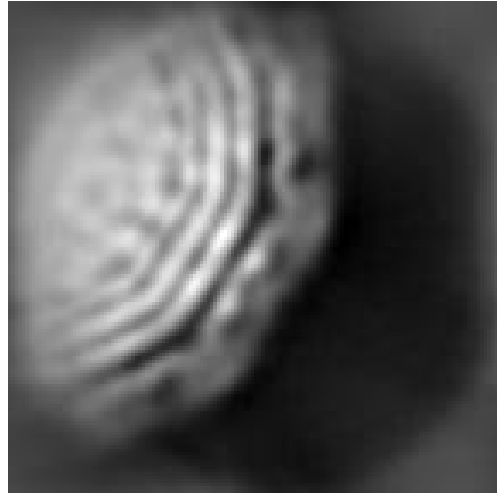
In the projections there should not be stripes (this is an indication of directional overweighting, or angular attraction), and there should not be a dark halo around or inside the structure (this is an indication of incorrect CTF correction or the reconstruction of a biased map).

Results:

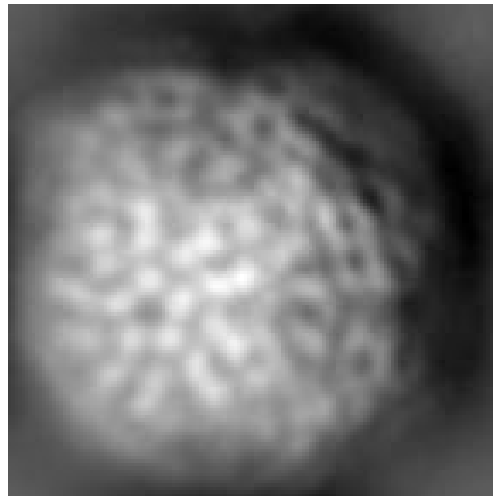
See Fig. [3](#).



(a) X Projection



(b) Y Projection



(c) Z Projection

Figure 3: Projections in the three dimensions

Isosurface views of the input map

Explanation:

An isosurface is the surface of all points that have the same gray value. In these views there should not be many artifacts or noise blobs around the map.

Results:

See Fig. 4.

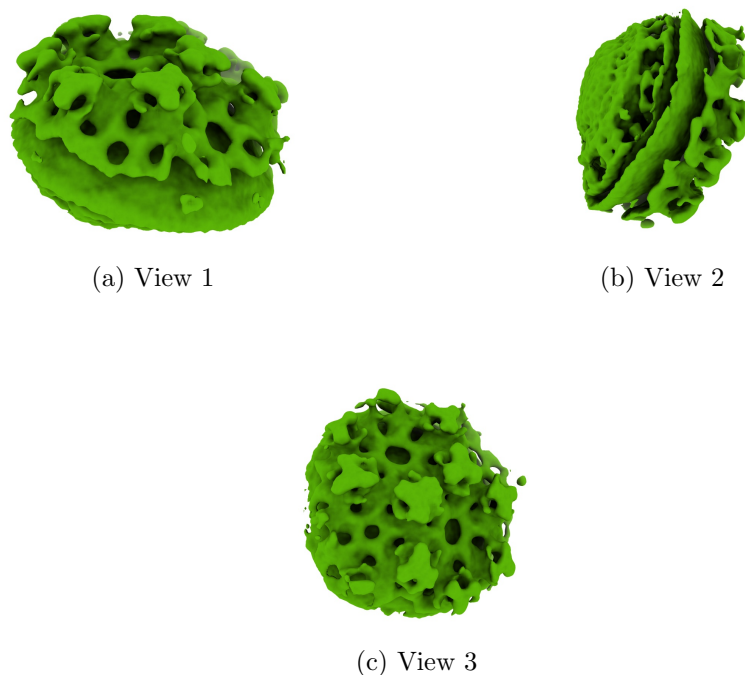


Figure 4: Isosurface at threshold=1.500000. Views generated by ChimeraX at a the following X, Y, Z angles: View 1 (0, -90, -90), View 2 (-90, 0, -90), View 3 (0, 0, 0).

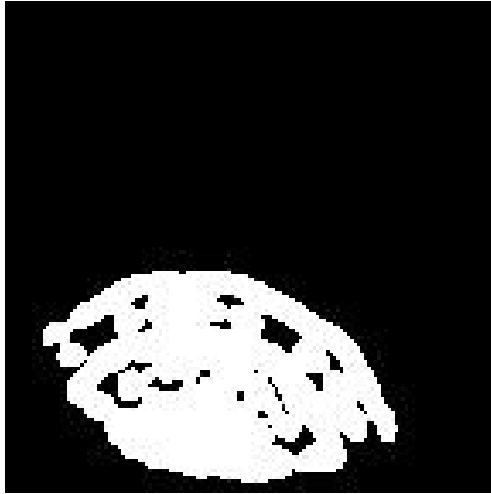
Orthogonal slices of maximum variance of the mask with hard borders

Explanation:

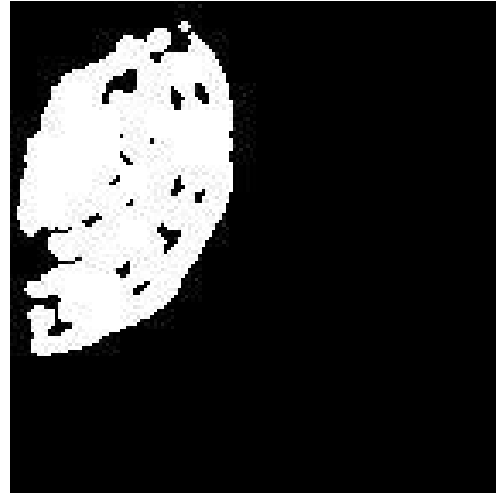
The mask with hard borders has been calculated at the suggested threshold 1.500000, the largest connected component was selected, and then dilated by 2Å.

Results:

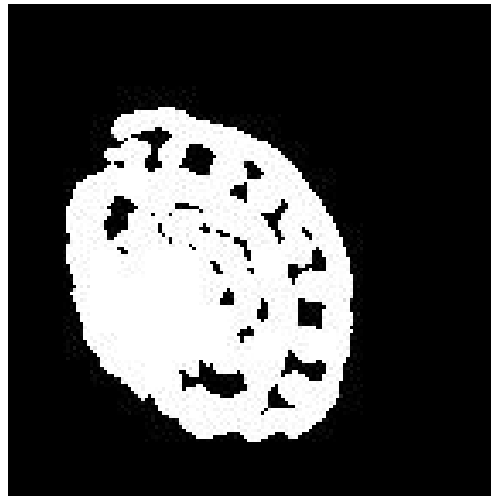
See Fig. 5.



(a) X Slice 47



(b) Y Slice 59



(c) Z Slice 23

Figure 5: Slices of maximum variation in the three dimensions of the mask with hard borders

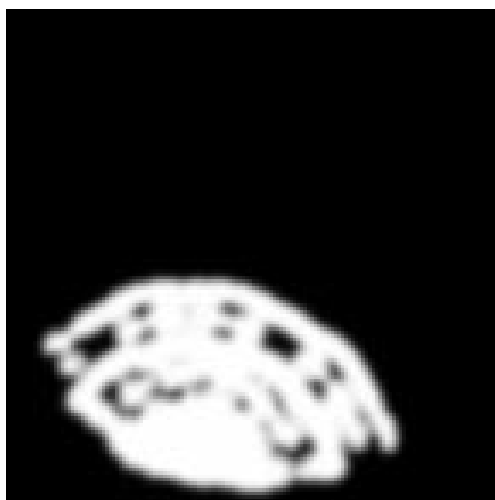
Orthogonal slices of maximum variance of the mask with soft borders

Explanation:

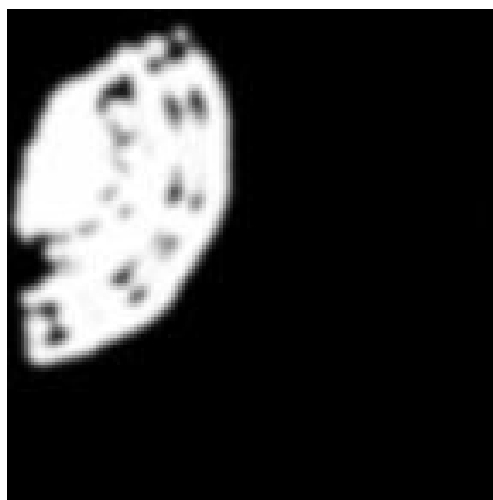
The mask with soft borders has been calculated at the suggested threshold 1.500000, the largest connected component was selected, and then dilated by

2Å.

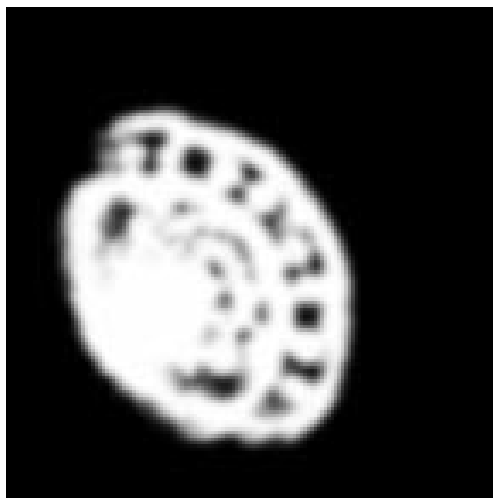
Results:
See Fig. 6.



(a) X Slice 47



(b) Y Slice 60



(c) Z Slice 23

Figure 6: Slices of maximum variation in the three dimensions of the mask with soft borders

2 Level 0 analysis

2.1 Level 0.a Mass analysis

Explanation:

The reconstructed map must be relatively well centered in the box, and there should be at least $30\text{\AA}$ (the exact size depends on the CTF) on each side to make sure that the CTF can be appropriately corrected.

Results:

The space from the left and right in X are 17.48 and $143.34\text{\AA}$, respectively. There is a decentering ratio $(\text{abs}(\text{Right-Left})/\text{Size})\%$ of 25.00%

The space from the left and right in Y are 34.96 and $104.88\text{\AA}$, respectively. There is a decentering ratio $(\text{abs}(\text{Right-Left})/\text{Size})\%$ of 13.89%

The space from the left and right in Z are 6.99 and $279.68\text{\AA}$, respectively. There is a decentering ratio $(\text{abs}(\text{Right-Left})/\text{Size})\%$ of 54.17%

The center of mass is at (x,y,z)=(-125710494.45,-74323608.66,-246849076.70). The decentering of the center of mass (abs(Center)/Size)% is 87299004.48, 51613667.12, and 171423019.93, respectively.

Automatic criteria: The validation is OK if 1) the decentering and center of mass less than 20% of the map dimensions in all directions, and 2) the extra space on each direction is more than 20% of the map dimensions. For local reconstruction, focused refinement, or similar, warnings are expected.

WARNINGS: 7 warnings

1. **The volume might be significantly decentered in X.**
2. **The volume might be significantly decentered in Z.**
3. **There could be little space from X left to effectively correct for the CTF.**
4. **There could be little space from Z left to effectively correct for the CTF.**
5. **The center of mass in X may be significantly shifted. This is common when the refinement is applied exclusively to one protein region.**
6. **The center of mass in Y may be significantly shifted. This is common when the refinement is applied exclusively to one protein region.**
7. **The center of mass in Z may be significantly shifted. This is common when the refinement is applied exclusively to one protein region.**

2.2 Level 0.b Mask analysis

Explanation:

The map at the suggested threshold should have most of its mass concentrated in a single connected component. It is normal that after thresholding there are a few thousands of very small, disconnected noise blobs. However, their total mass should not exceed 10%. The raw mask (just thresholding) and the mask constructed for the analysis (thresholding + largest connected component + dilation) should significantly overlap. Overlap is defined by

the overlapping coefficient ($\text{size(Raw AND Constructed)}/\text{size(Raw)}$) that is a number between 0 and 1, the closer to 1, the more they agree.

Results:

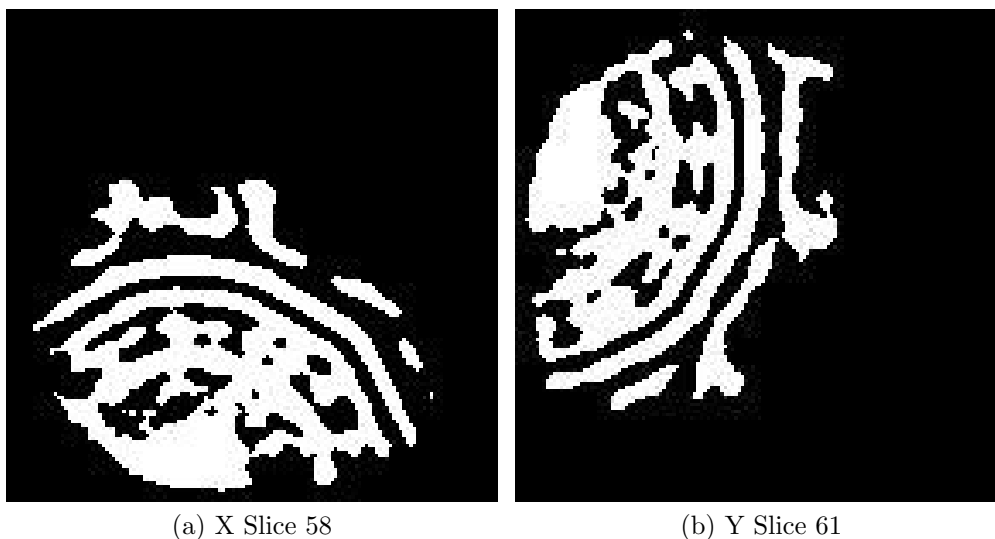
Raw mask: At threshold 1.500000, there are 22 connected components with a total number of voxels of 306040 and a volume of $13076528.52 \text{ \AA}^3$ (see Fig. 7). The size and percentage of the total number of voxels for the raw mask are listed below (up to 95% of the mass or the first 100 clusters, whatever happens first), the list contains (No. voxels (volume in $\text{\AA}^3$), percentage, cumulated percentage):

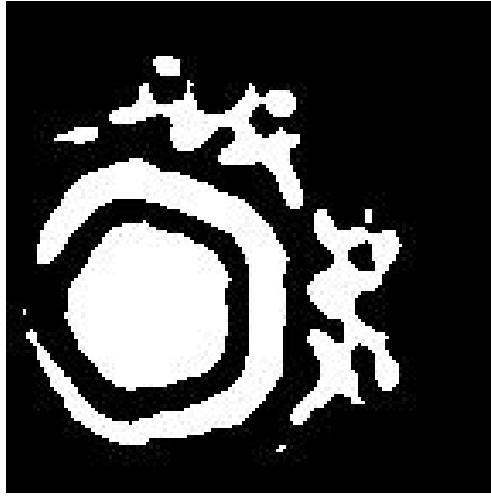
(163476 (6985029.98), 53.42, 53.42)(73563 (3143212.22), 24.04, 77.45)(68550 (2929015.91), 22.40, 99.85)

Number of components to reach 95% of the mass: 3

The average size of the remaining 19 components is 23.74 voxels ($42.73 \text{ \AA}^3$). Their size go from 68550 voxels ($2929015.91 \text{ \AA}^3$) to 1 voxels ($42.73 \text{ \AA}^3$).

The slices of the raw mask can be seen in Fig. 7.





(c) Z Slice 59

Figure 7: Maximum variance slices in the three dimensions of the raw mask

The following table shows the variation of the mass enclosed at different thresholds (see Fig. 8):

Threshold	Voxel mass	Molecular mass(kDa)	# Aminoacids
0.2004	796035.00	28179.88	256180.74
0.4008	701543.00	24834.84	225771.24
0.6012	621230.00	21991.73	199924.83
0.8017	548422.00	19414.31	176493.69
1.0021	478860.00	16951.79	154107.18
1.2025	413003.00	14620.43	132913.02
1.4029	342001.00	12106.94	110063.09
1.6033	269225.00	9530.65	86642.25
1.8037	209349.00	7411.02	67372.89
2.0042	165269.00	5850.57	53187.03
2.2046	131381.00	4650.93	42281.16
2.4050	104814.00	3710.45	33731.34
2.6054	83067.00	2940.60	26732.70
2.8058	64634.00	2288.06	20800.58
3.0062	49371.00	1747.75	15888.62
3.2066	36310.00	1285.39	11685.32
3.4071	25463.00	901.40	8194.53
3.6075	17185.00	608.35	5530.49
3.8079	11272.00	399.03	3627.57
4.0083	6809.00	241.04	2191.28
4.2087	3401.00	120.40	1094.51
4.4091	1214.00	42.98	390.69
4.6096	254.00	8.99	81.74
4.8100	20.00	0.71	6.44

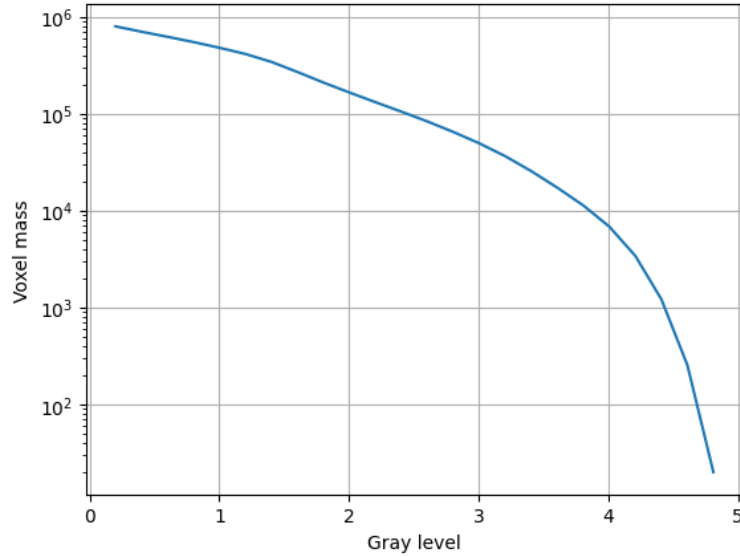


Figure 8: Voxel mass as a function of the gray level.

Constructed mask: After keeping the largest component of the previous mask and dilating it by $2\text{\AA}$, there is a total number of voxels of 247588 and a volume of $10578981.64 \text{ \AA}^3$. The overlap between the raw and constructed mask is 0.53.

Automatic criteria: The validation is OK if 1) to keep 95% of the mass we need to keep at most 5 connected components; and 2) the average volume of the blobs outside the given threshold has a size smaller than $5\text{\AA}^3$; and 3) the overlap between the raw mask and the mask constructed for the analysis is larger than 75%.

WARNINGS: 2 warnings

1. **There might be a problem with noise and artifacts, because the average noise blob has a volume of $42.728168 \text{ \AA}^3$.**
2. **There might be a problem in the construction of the mask, because the overlap is smaller than 0.75. A common reason is that the suggested threshold causes too many disconnected components.**

2.3 Level 0.c Background analysis

Explanation:

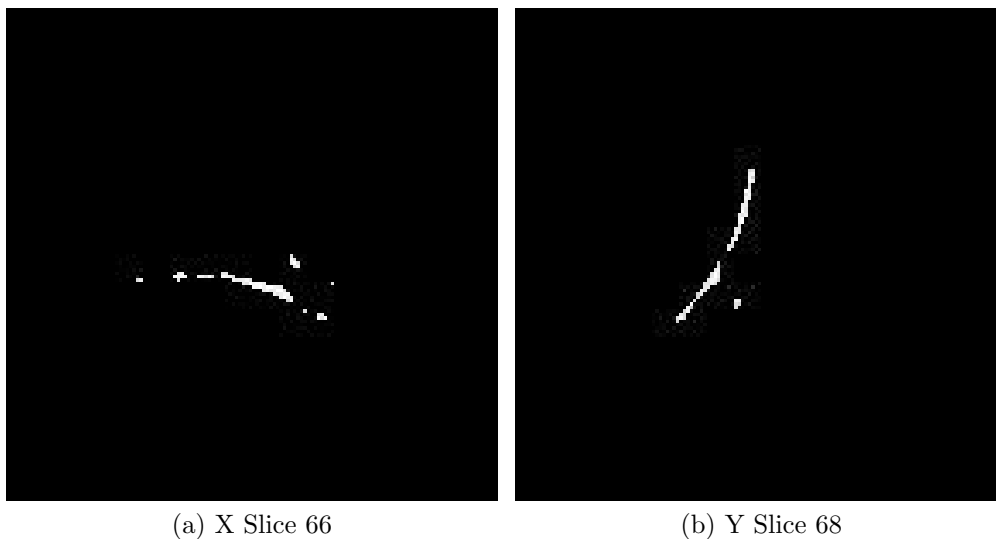
Background is defined as the region outside the macromolecule mask. The background mean should be zero, and the number of voxels with a very low or very high value (below 5 standard deviations of the noise) should be very small and they should be randomly distributed without any specific structure. Sometimes, you can see some structure due to the symmetry of the structure.

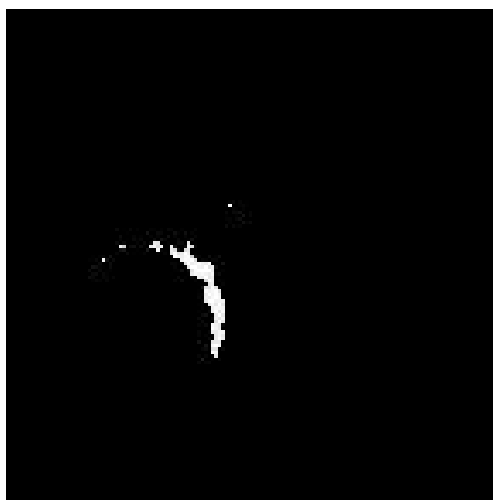
Results:

The null hypothesis that the background mean is 0 was tested with a one-sample Student's t-test. The resulting t-statistic and p-value were -309.89 and 0.000000, respectively.

The mean and standard deviation (sigma) of the background were -0.160809 and 0.858730. The percentage of background voxels whose absolute value is larger than 5 times the standard deviation is 0.08 % (see Fig. 9). The same percentage from a Gaussian would be 0.000057% (ratio between the two percentages: 1375.856615).

Slices of the background beyond 5*sigma can be seen in Fig. 9.





(c) Z Slice 67

Figure 9: Maximum variance slices in the three dimensions of the parts of the background beyond 5σ

Automatic criteria: The validation is OK if 1) the p-value of the null hypothesis that the background has 0 mean is larger than 0.001; and 2) the number of voxels above or below 5 sigma is smaller than 20 times the amount expected for a Gaussian with the same standard deviation whose mean is 0.

WARNINGS: 2 warnings

1. **The null hypothesis that the background mean is 0 has been rejected because the p-value of the comparison is smaller than 0.001**
2. **There is a significant proportion of outlier values in the background (cdf5 ratio=1375.86)**

2.4 Level 0.d B-factor analysis

Explanation:

The B-factor line (see this [link](#) for more details) fitted between $15\text{\AA}$ and the resolution reported should have a slope that is between 0 and $300\text{ \AA}^2$.

Results:

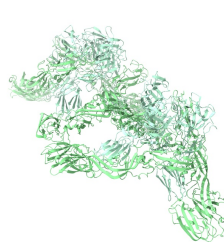
This method cannot be applied to maps with a resolution worse than 8Å.

STATUS: Does not apply

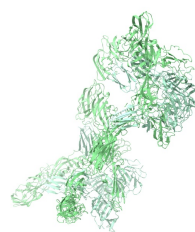
3 Atomic model

Atomic model: 7n69.cif

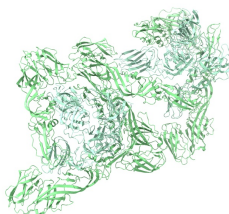
See Fig. 10.



(a) View 1



(b) View 2



(c) View 3

Figure 10: Input atomic model Views generated by ChimeraX at a the following X, Y, Z angles: View 1 (0, -90, -90), View 2 (-90, 0, -90), View 3 (0, 0, 0).

4 Level A Analysis

Map and model seem to be properly aligned.

4.1 Level A.a Phenix validation

Explanation:

Phenix provides a number of tools to assess the agreement between the experimental map and its atomic model (see this [link](#) for more details). There are several cross-correlations to assess the quality of the fitting:

- CC (mask): Model map vs. experimental map correlation coefficient calculated considering map values inside a mask calculated around the macromolecule.
- CC (box): Model map vs. experimental map correlation coefficient calculated considering all grid points of the box.
- CC (volume) and CC (peaks) compare only map regions with the highest density values and regions below a certain contouring threshold level are ignored. CC (volume): The map region considered is defined by the N highest points inside the molecular mask. CC (peaks): In this case, calculations consider the union of regions defined by the N highest peaks in the model-calculated map and the N highest peaks in the experimental map.
- Local real-space correlation coefficients CC (main chain) and CC (side chain) involve the main skeleton chain and side chains, respectively.

There are also multiple ways of measuring the resolution:

- d99: Resolution cutoff beyond which Fourier map coefficients are negligibly small. Calculated from the full map.
- d_model: Resolution cutoff at which the model map is the most similar to the target (experimental) map. For d_model to be meaningful, the model is expected to fit the map as well as possible. d_model (B factors = 0) tries to avoid the blurring of the map.
- d_FSC_model; Resolution cutoff up to which the model and map Fourier coefficients are similar at FSC values of 0, 0.143, 0.5.

In addition to these resolution measurements the overall isotropic B factor is another indirect measure of the quality of the map.

Results:

To avoid ringing in Fourier space a smooth mask with a radius of 28.2 Å has been applied.

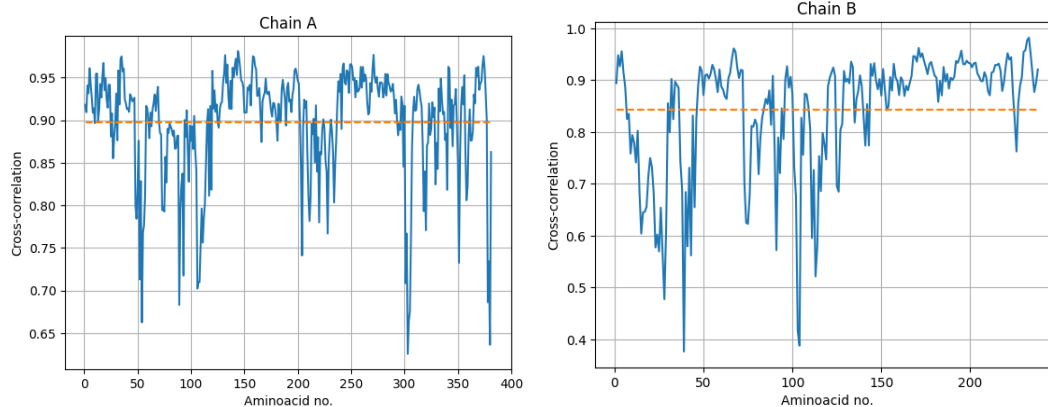
Overall correlation coefficients:

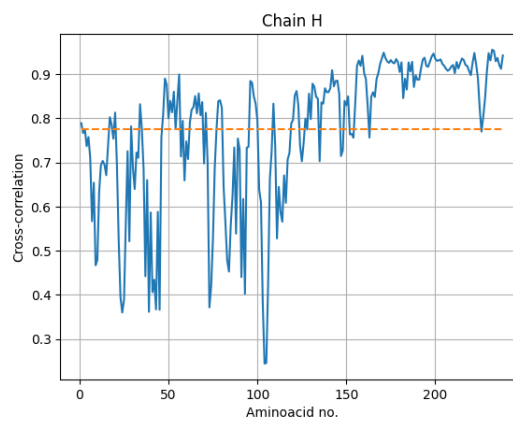
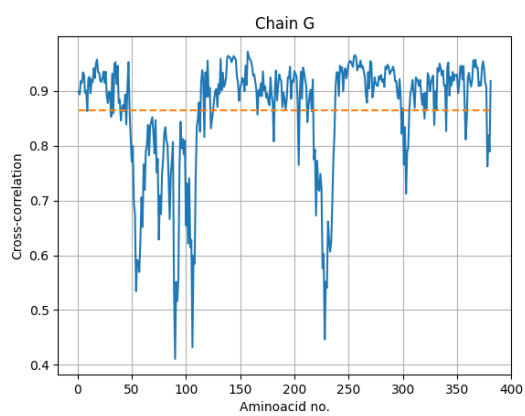
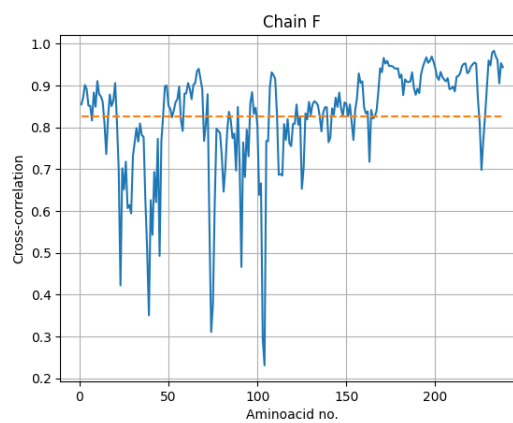
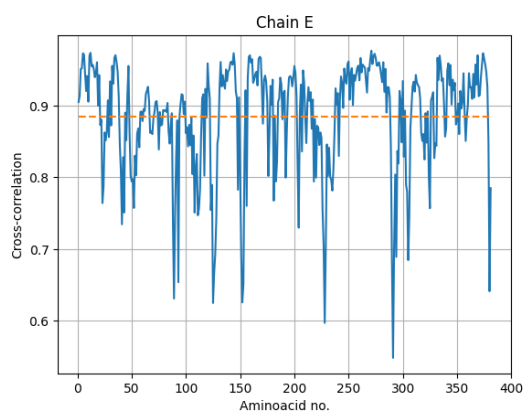
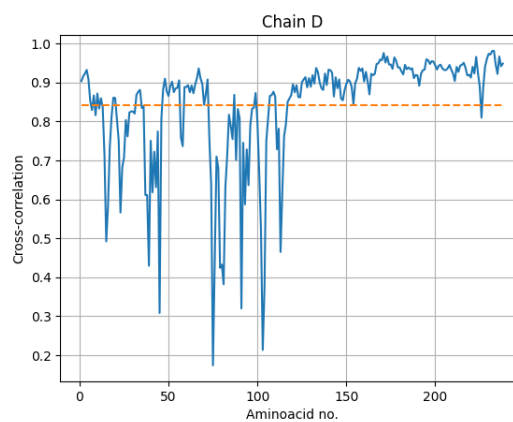
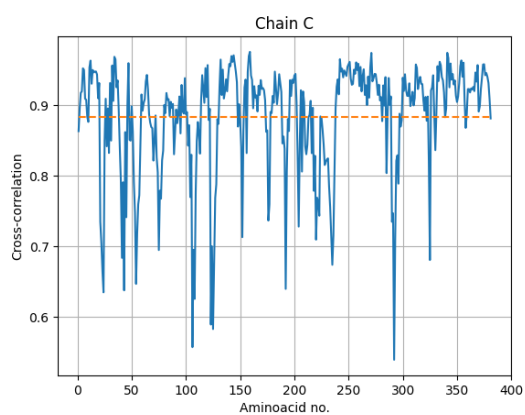
CC (mask) =	0.696
CC (box) =	0.345
CC (volume) =	0.672
CC (peaks) =	-0.535
CC (main chain) =	0.804
CC (side chain) =	0.798

Correlation coefficients per chain:

Chain	Cross-correlation
A	0.836739
B	0.831127
C	0.792080
D	0.842193
E	0.791801
F	0.818768
G	0.818006
H	0.796155
I	0.801994
J	0.781731
K	0.767748
L	0.804369

We now show the correlation profiles of the different chain per residue.





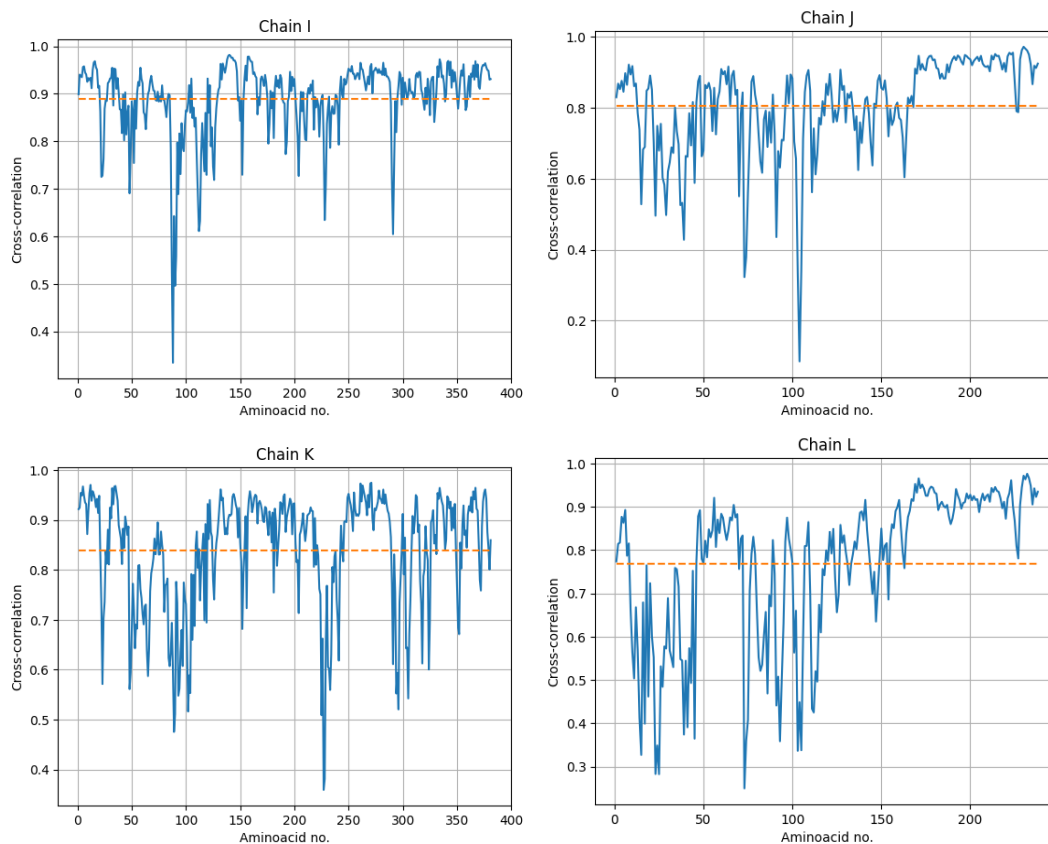


Fig. 11 shows the histogram of all cross-correlations evaluated at the residues. The percentage of residues whose correlation is below 0.5 is 2.3 %.

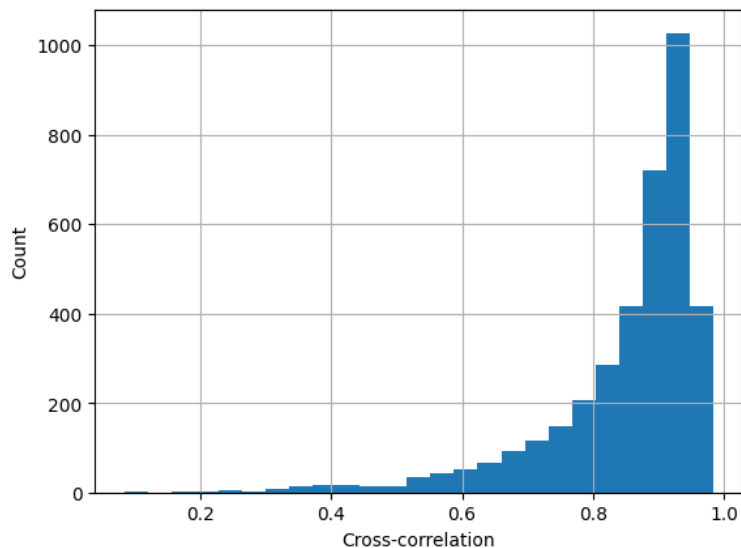


Figure 11: Histogram of the cross-correlation between the map and model evaluated for all residues.

Resolutions estimated from the model:

Resolution (Å)	Masked	Unmasked
d99	16.7	14.1

Automatic criteria: The validation is OK if 1) the percentage of residues whose correlation is smaller than 0.5 is smaller than 10%, and 2) the resolution reported by the user is larger than 0.8 times the resolution estimated between the map and model at FSC=0.5.

WARNINGS: 1 warnings

1. **The model-map FSC resolution value (FSC=0.5) is missing. Skipping consistency check with the user-reported resolution.**

4.2 Level A.d Map-Model Guinier analysis

This method cannot be applied to maps with a resolution worse than 8Å.

STATUS: Does not apply

4.3 Level A.e MapQ

Explanation:

MapQ (see this [link](#) for more details) computes the local correlation between the map and each one of its atoms assumed to have a Gaussian shape.

Results:

This method cannot be applied to maps with a resolution worse than 5Å.

STATUS: Does not apply

4.4 Level A.f EMRinger validation

Explanation:

EMRinger (see this [link](#) for more details) compares the side chains of the atomic model to the CryoEM map. The following features are reported:

- Optimal Threshold: Electron potential map cutoff value at which the maximum EMRinger score was obtained.
- Rotamer Ratio: Fraction of rotameric residues at the Optimal threshold value.
- Max Zscore: Z-score computed to determine the significance of the distribution at the Optimal threshold value.
- Model Length: Total of non-gamma-branched, non-proline aminoacids with a non-H gamma atom used in global EMRinger score computation.
- EMRinger Score: Maximum EMRinger score calculated at the Optimal Threshold.

A rotameric residue is one in which EMRinger peaks that fall within defined rotamers based on chi1, this often suggests a problem with the modelling of the backbone. In general, the user should look at the profiles and identify regions that may need improvement.

Results:

This method cannot be applied to maps with a resolution worse than 5Å.

STATUS: Does not apply

4.5 Level A.g DAQ validation

Explanation:

DAQ (see this [link](#) for more details) is a computational tool using deep learning that can estimate the residue-wise local quality for protein models from cryo-Electron Microscopy maps. The method calculates the likelihood that a given density feature corresponds to an aminoacid, atom, and secondary structure. These likelihoods are combined into a score that ranges from -1 (bad quality) to 1 (good quality).

Results:

This method cannot be applied to maps with a resolution worse than 5Å.

STATUS: Does not apply